

a complete and detailed derivation  
of the formula

*Misra*

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(1)  $F = \chi_2 m H \frac{dH}{dx}$  and  
its limitations.

We begin by observing law (and MKS system)

(2)  $\vec{j} = \sigma (\vec{E} + \vec{E}')$  where  $\vec{j}$  is the true current density,  $\vec{E}$  is an irrotational vector field derivable from a scalar potential function (i.e. electric field set up by fixed distribution of charge);  $\vec{E}'$  is a field which is not derivable from a scalar potential <sup>and</sup> which is maintained by some source (e.g., battery) producing <sup>a steady</sup> ~~the~~ current flow; ~~it is produced by~~.  $\sigma$  is <sup>the</sup> conductivity of <sup>the</sup> medium. Then  $\frac{\partial \vec{j}}{\partial \tau} = 0$  for all space and which implies  $\frac{\partial \vec{E}'}{\partial \tau} = 0$ . ~~it is constant over~~

Now from (2)  $\vec{E}' = \frac{\vec{j}}{\sigma} - \vec{E}$  hence

$$(3) \vec{j} \cdot \vec{E}' = \vec{j} \cdot \left( \frac{\vec{j}}{\sigma} - \vec{E} \right) = \frac{\vec{j}^2}{\sigma} - \vec{j} \cdot \vec{E} \quad (\vec{j}^2 = \vec{j} \cdot \vec{j} = j^2)$$

we now integrate (3) over all space

$$(4) \iiint \vec{j} \cdot \vec{E}' dv = \iiint \frac{\vec{j}^2}{\sigma} dv - \iint \vec{j} \cdot \vec{E} dv$$

The term on the left hand side of above equation represents the total rate of flow of energy from the source producing  $\vec{E}$ . Since this source is the only energy producing source in our system the terms on the right must sum to the total consumption of energy. now resistance at any point in our media is the reciprocal of its conductivity at that particular point hence the term  $\iiint \frac{j^2}{\sigma} dv$  represents the total power dissipated due to resistance of our medium to current flow. The term  $\iiint \vec{j} \cdot \vec{E} dv$  must then be associated with rate of energy flow used in maintaining the resulting magnetic field (due to the assumption of an electric field  $\vec{E}$  existing).

We now make use of Maxwell's field equations:

$$(5) \quad \nabla \times \vec{E} + \frac{\partial \vec{B}}{\partial t} = 0$$

$$(6) \quad \nabla \times \vec{H} - \frac{\partial \vec{D}}{\partial t} = \vec{j}$$

for stationary current flow and media,

$$\frac{\partial \vec{D}}{\partial t} = 0 \quad \text{hence } \vec{j} = \nabla \times \vec{H}$$

Thus  $-\iiint_V \vec{j} \cdot \vec{E} dv = -\iiint_V \nabla \times \vec{H} \cdot \vec{E} dv$  and observing  
the vector identity

$$\nabla \cdot \vec{E} \times \vec{H} = -\vec{E} \cdot \nabla \times \vec{H} + \vec{H} \cdot \nabla \times \vec{E}$$

we obtain

$$-\iiint_V \vec{j} \cdot \vec{E} dv = \iiint_V \nabla \cdot \vec{E} \times \vec{H} dv - \iiint_V \vec{H} \cdot \nabla \times \vec{E} dv$$

and by (5) we write

$$-\iiint_V \vec{j} \cdot \vec{E} dv = \iiint_V \nabla \cdot \vec{E} \times \vec{H} dv + \iiint_V \vec{H} \cdot \frac{\partial \vec{B}}{\partial t} dv$$

By the divergence theorem we obtain

$$\iiint_V \nabla \cdot \vec{E} \times \vec{H} dv = \iint_S \vec{E} \times \vec{H} \cdot d\vec{s} \quad \text{where } S \text{ is the}$$

surface bounding  $V$ . But since  $\vec{E} \times \vec{H}$  falls off at least as  $\frac{1}{r^2}$  the term  $\iint_S \vec{E} \times \vec{H} \cdot d\vec{s} = 0$

$$\therefore \iiint_V \vec{j} \cdot \vec{E}' dv = \iiint_V \frac{j^2}{\sigma} dv + \iiint_V \vec{H} \cdot \frac{\partial \vec{B}}{\partial t} dv$$

Let  $w$  denote the work required to maintain our magnetic field. Then

$$\frac{dw}{dt} = \iiint_V \vec{H} \cdot \frac{\partial \vec{B}}{\partial t} dv \quad \text{During a small time interval}$$

$\delta w = \iiint_V \vec{H} \cdot \delta \vec{B} dv$  Hence when the field reaches a stationary state the total energy it contains (ie the total amount of

work it took to set it up) is equal to  $w$ .

$$(7) \quad w = \int_0^B \delta w = \int_0^B \iiint_V \vec{H} \cdot \delta \vec{B} dv = \iiint_V \left( \int_0^B \vec{H} \cdot \delta \vec{B} \right) dv$$

Now  $\vec{H}$  is defined as :

$$(8) \quad \vec{H} = \frac{1}{\mu_0} (\vec{B} - \mu_0 \vec{M}) = \frac{\vec{B}}{\mu_0} - \vec{M} \quad \text{where } \vec{M}$$

is magnetization of medium. It depends on the applied field  $\vec{B}$  by the equation

$$(9) \quad \vec{M} = \chi_m \vec{H} \quad \text{where } \chi_m \text{ is called the magnetic susceptibility.}$$

We now reach a critical point in our reasoning.

For most media  $\vec{M}$  is ~~perp~~  $\parallel$  to  $\vec{H}$ . But for so called ferromagnetic media  $\vec{M}$  is not  $\parallel$  to  $\vec{H}$  and hence  $\chi_m$  becomes a tensor, not a single scalar. If  $\vec{M}$  is approximately  $\parallel$  to  $\vec{H}$ , then  $\chi_m$  can be assumed to be a scalar. The magnitude of error now introduced as we proceed depends upon the magnitude of magnetization of media under consideration.

We take  $\chi_m$  to be a scalar.

$$\vec{M} = \chi_m \vec{H}$$

From from (8)  $\vec{B} = \mu_0 \vec{H} + \vec{M}$

$$\begin{aligned} &= \mu_0 \vec{H} + \chi_m \vec{H} \\ &= \mu_0 (1 + \chi_m) \vec{H} \\ &= \mu_0 K_m \vec{H} \end{aligned}$$

$$(9) \quad \vec{B} = \mu_0 K_m \vec{H} \quad \text{where } K_m = 1 + \chi_m$$

and is called relative permeability of the medium. Now employing this result in (7) we write

$$w = \iiint_V \left( \int_0^{\vec{B}} \vec{H} \cdot d\vec{B} \right) dv = \iiint_V \left( \int_0^{\vec{B}} \frac{\vec{B}}{\mu_0 K_m} \cdot d\vec{B} \right) dv$$

$$= \iiint_V \int_0^{\vec{B}} \frac{d\vec{B}^2}{2\mu_0 K_m} dv$$

$$\text{But } \int_0^{\vec{B}} \frac{d\vec{B}^2}{2\mu_0 K_m} = \frac{\vec{B}^2}{2\mu_0 K_m} = \frac{\mu_0 K_m \vec{H}^2}{2\mu_0 K_m} = \frac{1}{2} \mu_0 K_m \vec{H}^2$$

$$\therefore w = \iiint_V \frac{1}{2} \mu_0 K_m \vec{H}^2 dv$$

Let us now introduce a small sample of new media with relative permeability equal to  $K_m'$  and denoting  $K_m'$  to be the relative permeability of original media. We assume that

$$\vec{M} = \chi_m \vec{H} \quad \chi_m = \text{a scalar}$$

for this new medium even though our new medium will be ferrimagnetic!

Thus the energy stored in the magnetic field will change by an amount

$$\Delta W = \frac{1}{2} \mu_0 \left[ \iiint_V K'_m \vec{H}^2 dV - \iiint_{V_s} K'_m \vec{H}^2 dV - \iiint_{V_e} K_m \vec{H}^2 dV \right]$$

where  $V$  of course represents all space.  $V_s' = V - V_s$ ,  $V_s$  is region occupied by new medium.

$$\therefore \Delta W = \iiint_{V_s} \frac{\mu_0}{2} (K'_m - K_m) \vec{H}^2 dV$$

If  $V_s$  is sufficiently small such that  $\vec{H}$  is nearly constant throughout it, we may write

$$\Delta W = \frac{1}{2} \mu_0 (K'_m - K_m) H^2 V_s \quad \text{or}$$

$$\Delta W = \frac{1}{2} \mu_0 (X'_m - X_m) H^2 V_s$$

where  $V_s$  is the volume occupied by the new medium. ( $X_m$  &  $X'_m$  are volume res.)

To account account for this energy change is an easy matter. It goes into the energy of position or simply the potential energy of the new medium.

$$U = \Delta W = \frac{1}{2} \mu_0 (X'_m - X_m) H^2 V_s$$

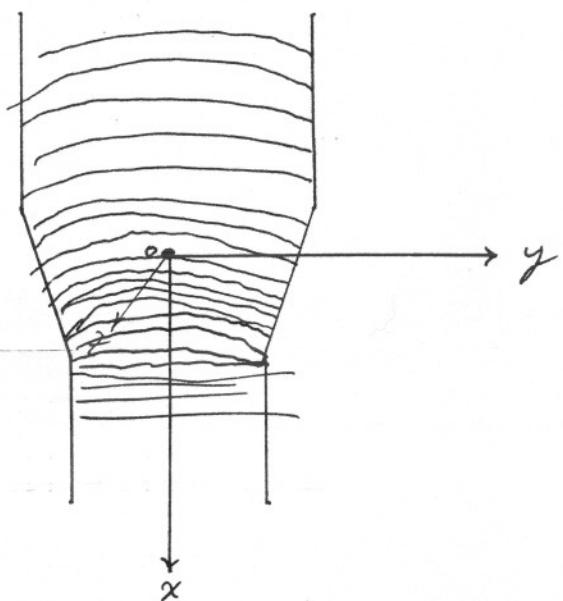
Since this field itself is conservative any force acting on the new medium is

equal to the negative gradient of its potential function  $V$ .

$$\begin{aligned}\therefore \vec{F} &= -\nabla V \\ &= -\left(\frac{\partial V}{\partial x} \hat{i} + \frac{\partial V}{\partial y} \hat{j} + \frac{\partial V}{\partial z} \hat{k}\right)\end{aligned}$$

where  $\hat{i}, \hat{j}, \hat{k}$  are unit vectors in a chosen rectangular coordinate system.

Our field will in general appear as indicated below, hence we take the coordinate system as indicated with the  $z$  coordinate coming out of paper.



Hence we have  $\frac{\partial H}{\partial y} = \frac{\partial H}{\partial z} = 0$  and thus

$$\begin{aligned}\vec{F} &= -\frac{\partial V}{\partial x} \hat{i} = -\frac{1}{2} \mu_0 \left( \frac{1}{2} \mu_0 (x_m' - x_m) H^2 V_s \right) \hat{i} \\ &= -\frac{1}{2} \mu_0 (x_m' - x_m) V_s \cdot 2 H \frac{\partial H}{\partial x} \hat{i}\end{aligned}$$

Hence

$$\vec{F} = \mu_0 (X_m - X'_m) V_s H \frac{\partial H}{\partial x} \hat{i}$$

If the original medium ~~is~~ is air

$X'_m \approx 0$  and we write

$$(10) \quad \vec{F} = \mu_0 X_m V_s H \frac{\partial H}{\partial x} \hat{i}$$

$F$  is in newtons

$\mu_0$  is  $4\pi \times 10^{-7}$  ~~newton~~  $m$ ,  $V_s$  is in  $m^3$ ,  $H$  is in ~~ampere turns~~  $m$

The dimension of  $X_m$  is then fixed. (mass in kgm)

In CGS (electromagnetic) system  $\mu_0$  is unity

$F$  in dynes,  $H$  in oersted,  $B$  in gauss,  $V_s$  in  $cm^3$

In both systems the volume res. equals the gram res. multiplied by its density.

$$X_m = X_g d$$

$$\therefore \text{in CGS} \quad F = X_g m H \frac{\partial H}{\partial x}$$

~~for this derivation various~~

~~assumptions exist and it is impossible for (10) to be true without grouping like terms.~~

~~The formula (10) for~~  
~~presupposes linearity between  $M$  &  $H$ ; also that~~  
~~the law of~~ and its ability  
to predict values of susceptibility ~~should~~  
of strong ferrimagnetic substances ~~should~~  
~~not to be realized.~~